

Goal: use Lyapunov method for convergence analysis of optimization algorithms

- Assume, you like to find the minimizer of the function $J: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\min_{x \in \mathbb{R}^n} J(x) \quad \rightarrow \text{training NN}$$

- A classical alg. is gradient descent: (we assume J is differentiable)

$$x_{k+1} = x_k - \eta \nabla J(x_k)$$

η step-size

- In the cont. time limit, as $\eta \rightarrow 0$, this update converges to gradient flow:

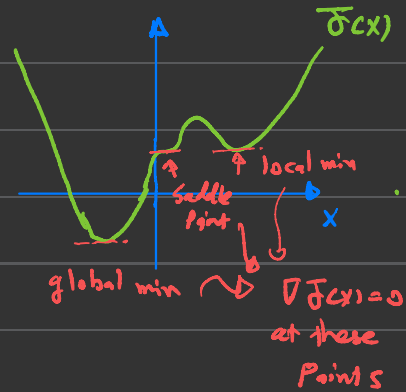
$$\dot{x} = -\nabla J(x)$$

- We will use Lyapunov method to analyze convergence of gradient flow \rightarrow gives insight about conv. of grad. descent.

- Eq/b. points:

$$E = \{x \in \mathbb{R}^n; \nabla J(x) = 0\}$$

→ Critical/Extreme points



- Any global minimizer x^* is a critical point

$\nabla J(x^*) = 0$ → 1st-order necessary condition for optimality.

- Our goal is to analyze the convergence of gradient flow under different assumptions on the obj. function $J(x)$

Case 1: No assumption

Case 2: radially unbounded

Case 3: Convex

Case 4: gradient dominance

Case 5: strongly convex.

Case 1: (No assumption on J)

- let $V(x) = f(x) - \underbrace{f(x^*)}_{\min_x f(x)}$, then

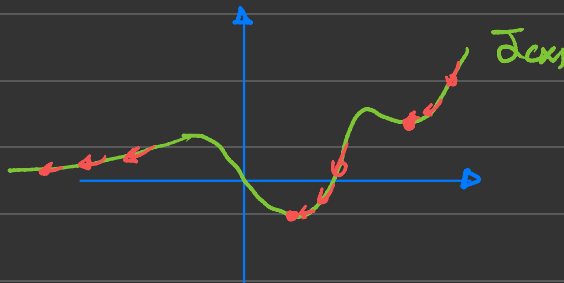
$$\begin{aligned} \frac{d}{dt} V(x_{(t)}) &= \nabla V(x_{(t)}) \cdot (-\nabla f(x_{(t)})) \\ &= -\|\nabla f(x_{(t)})\|_2^2 \end{aligned}$$

- Integrating with respect to time:

$$V(x_{(t)}) - V(x_{(0)}) = -\int_0^t \|\nabla f(x_{(s)})\|_2^2 ds \leq -t \min_{S \in [0, t]} \|\nabla f(x_{(s)})\|_2^2$$

$$\Leftrightarrow \min_{S \in [0, t]} \|\nabla f(x_{(s)})\|_2^2 \leq \frac{V(x_{(t)}) - V(x_{(0)})}{t} \leq \frac{f(x_{(t)}) - f(x^*)}{t}$$

- Easiest conv. result under no assumption $\mathcal{O}(\frac{1}{t})$ convergence



Case 2: (J is radially unbounded)

- In this case, $V(x) = F(x) - F(x^*)$ is a radially unbounded

function and $\dot{V}(x) = -\|\nabla F(x)\|_2^2 \leq 0 \quad \forall x$.

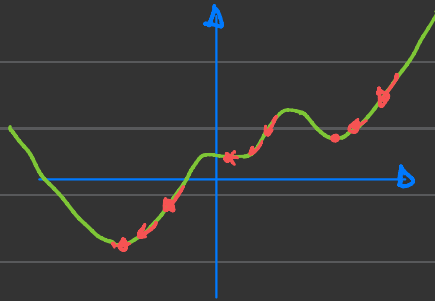
\Rightarrow all solutions are bounded

LaSalle

$\Rightarrow x(t) \rightarrow E = \{x \in \mathbb{R}^n; \nabla F(x) = 0\}$

\rightarrow Largest invariant set in E is E

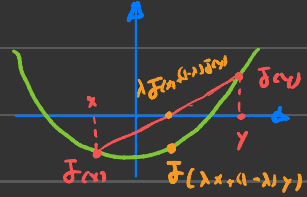
$\Rightarrow x(t)$ converges to a critical point!



- We can do the linearization procedure to obtain local convergence regions, and local convergence rates.

Convex analysis : [Rockafellar]

- $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex if

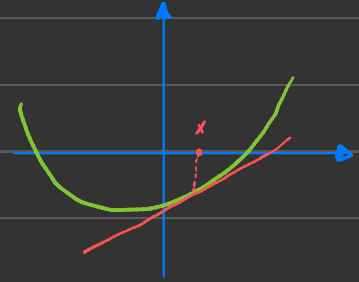


$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y), \quad \forall x, y \in \mathbb{R}^n \\ \forall \lambda \in [0, 1]$$

- A convex func is always locally Lip. on its domain (diff almost everywhere)
- If f is diff. everywhere, then

$$f(y) \geq f(x) + \nabla f(x)(y-x), \quad \forall x, y \in \mathbb{R}^n$$

graph lies above
its tangents



- For convex functions:

all critical points are global minimizers

why?

$$\nabla f(x) = 0 \Rightarrow f(y) \geq f(x) \quad \forall y \Rightarrow x \text{ is global minimizer}$$

Case 3: (f is convex)

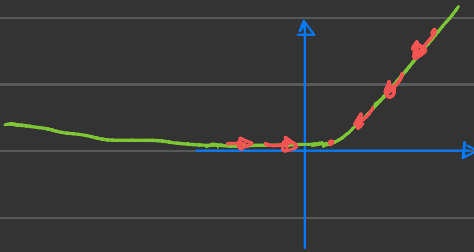
- Take $V(t, x) = \frac{1}{2} \|x - x^*\|^2 + t(f(x) - f(x^*))$

- Then, $\frac{d}{dt} V(t, x(t)) = (x(t) - x^*)^T (-\nabla f(x(t))) + f(x(t)) - f(x^*) - t \|\nabla f(x(t))\|^2 \leq 0$

- Integrating: $V(t, x(t)) \leq V(0, x(0)) = \frac{1}{2} \|x(0) - x^*\|^2$

$$\Rightarrow f(x(t)) - f(x^*) \leq \frac{1}{2t} \|x(0) - x^*\|^2$$

$O(\frac{1}{t})$ convergence of
value of obj. func.



→ Poljak - Łojasiewicz

Gradient. dominance or PL condition:

$$f(x) - f(x^*) \leq \frac{1}{2\mu} \|\nabla f(x)\|_2^2 \quad \forall x$$

Case 4: (f is not convex, but satisfies PL condition)

- Take $V(x) = f(x) - f(x^*)$, then

$$\frac{d}{dt} V(x(t)) = -\|\nabla f(x)\|_2^2 \leq -2\mu V(x(t))$$

Comparison

→
lemma

$$V(x(t)) \leq e^{-2\mu t} V(x_0)$$

$$\Rightarrow f(x(t)) - f(x^*) \leq e^{-2\mu t} (f(x_0) - f(x^*))$$

↓

exp. convergence

Strongly Convex Functions:

- $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is μ -strongly convex if

$$f(y) \geq f(x) + \nabla f(x)(y-x) + \frac{\mu}{2} \|y-x\|^2$$

Case 5: (f is strongly convex)

- let $V(x) = \frac{1}{2} \|x - x^*\|^2 \Rightarrow$

$$\frac{d}{dt} V(x(t)) = \nabla f(x(t))(x^* - x(t))$$

- Strong convexity condition for $y = x^*$ and $x = x(t)$ implies

$$\begin{aligned} \nabla f(x(t))(x^* - x(t)) &\leq \underbrace{f(x^*) - f(x(t))}_{\leq 0} - \frac{\mu}{2} \underbrace{\|x(t) - x^*\|^2}_{V(x(t))} \\ &\leq -\mu V(x(t)) \end{aligned}$$

$$\begin{aligned} \Rightarrow \frac{d}{dt} V(x(t)) &\leq -\mu V(x(t)) \Rightarrow V(x(t)) \leq e^{-t\mu} V(x(0)) \\ &\Rightarrow \underbrace{\|x(t) - x^*\|^2}_{\text{exp. convergence!}} \leq e^{-2t\mu} \|x(0) - x^*\|^2 \end{aligned}$$

Remark:

- Strong convexity \implies PL
- Some PL functions are not convex, and convex functions are not PL

Summary:

